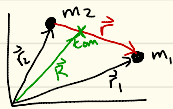


Recap: 2 bodies interacting via Central Forces (ch 8)

$$\vec{F}_{12} = -\vec{F}_{21} \equiv \vec{F}, \quad \text{central force further says } \vec{F} = \hat{r} F(r)$$



$$\vec{R} = \frac{m_1 \vec{r}_1 + m_2 \vec{r}_2}{M}, \quad \vec{r} = \vec{r}_1 - \vec{r}_2$$

* Writing $\vec{F}_{12} = m_1 \ddot{\vec{r}}_1 + \vec{F}_{21} = m_2 \ddot{\vec{r}}_2$ in terms of (\vec{r}, \vec{R})

$$\Rightarrow \begin{cases} M \ddot{\vec{R}} = 0 \\ \mu \ddot{\vec{r}} = \vec{F}(\vec{r}) \end{cases}$$

→ i.e., \vec{R} & \vec{r} dynamics decouple
Motion of \vec{R} trivial (free particle)

⇒ effective 1-body problem
(Work in COM frame $\vec{R} \equiv 0$)

* Assuming $\vec{F}(\vec{r}) = -\vec{\nabla} U(r)$ and $\vec{F} = \hat{r} F(r)$ (i.e., conservative central force)

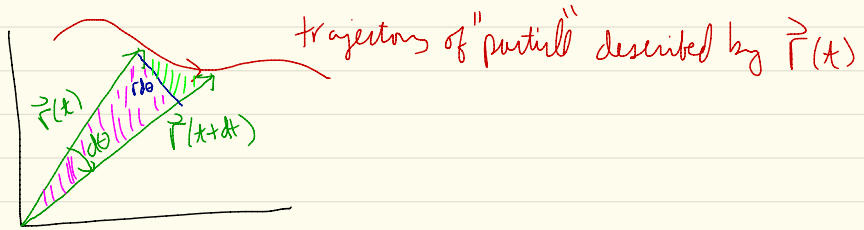
$$\Rightarrow \begin{cases} E = \frac{1}{2} \mu \dot{\vec{r}}^2 + U(r) = \text{constant (i.e., conserved)} \\ \vec{L} = \vec{r} \times \vec{p} \quad (\vec{p} = \mu \dot{\vec{r}}) = \text{constant} \end{cases}$$

$\frac{d\vec{L}}{dt} = 0 \Rightarrow$ motion lies in plane \perp to constant \vec{L} (i.e., $\vec{r}, \vec{p} \perp \vec{L}$)
∴ effective 2D prob. (Polar coords)

$$|\vec{L}| \equiv \ell = \mu r^2 \dot{\theta}$$

$$E = \frac{1}{2} \mu \dot{r}^2 + \frac{1}{2} \mu r^2 \dot{\theta}^2 + U(r) = \frac{1}{2} \mu \dot{r}^2 + \frac{1}{2} \frac{\ell^2}{\mu r^2} + U(r)$$

Ex: Kepler's 2nd Law (Constant "areal velocity")



$$dA = \text{area swept out by } \vec{r} \text{ in } (t, t+dt) = \text{pink triangle area} + \text{green triangle area}$$
$$= \frac{1}{2} r^2 d\theta$$

$$\Rightarrow \frac{dA}{dt} = \frac{1}{2} r^2 \dot{\theta}$$

use $\dot{\theta} = \frac{L}{\mu r^2}$

$$\Rightarrow \boxed{\frac{dA}{dt} = \frac{1}{2} \frac{L}{\mu} = \text{constant}}$$

i.e., equal area swept out by $\vec{r}(t)$ in equal time intervals

From E, l eqns, we can formally (i.e., not always useful in a practical sense due to nasty integrals) solve for r, θ

$$\frac{dr}{dt} = \sqrt{\frac{2}{m} \left[E - U - \frac{1}{2} \frac{l^2}{mr^2} \right]} \Rightarrow t = \int_{r_0}^r \frac{dr}{\sqrt{\frac{2}{m} \left[E - U - \frac{1}{2} \frac{l^2}{mr^2} \right]}} \quad (1)$$

(i.e., gives $t = t(r)$). Can be (formally) inverted to give $r = r(t)$.

*Turning to θ :

$$d\theta = \frac{d\theta}{dt} \frac{dt}{dr} dr = \frac{\dot{\theta}}{\dot{r}} dr \quad \text{use } \dot{\theta} = \frac{l}{mr^2}$$

$$\Rightarrow d\theta = \frac{l/mr^2}{\sqrt{\frac{2}{m} \left[E - U - \frac{1}{2} \frac{l^2}{mr^2} \right]}} dr$$

$$\Rightarrow \Theta(r) = \int_{r_0}^r \frac{\frac{l}{r^2} dr}{\sqrt{2\mu \left(E - U - \frac{1}{2} \frac{l^2}{mr^2} \right)}} \quad (2)$$

* (1) + (2) formally solve the problem, but not always useful if $U(r)$ too complicated + integral can't be done.

- turns out for $F(r) \propto r^n$ (hence $U(r) \propto r^{n+1}$),
 $n = 5, 3, 0, -4, -5, -7$ can be expressed as "Elliptic Integrals"
 that can be looked up in tables

- for $n = 1, -2, -3$, can be expressed in terms of trig functions

Alternative way to solve the problem directly from Newton's EOM

* Rather than solving for $r(t)$, sometimes it's useful to find $r = r(\theta)$. Here, it's best done directly via the $\vec{F} = m\vec{a}$ eqns.

$$m\vec{\ddot{r}} = \hat{r}F(r) \quad \vec{\ddot{r}} = (\ddot{r} - r\dot{\theta}^2)\hat{r} + (r\ddot{\theta} + 2\dot{r}\dot{\theta})\hat{\theta}$$

$$\begin{aligned} \Rightarrow m(\ddot{r} - r\dot{\theta}^2) &= F(r) = -\frac{\partial U}{\partial r} & \textcircled{1} \\ m(r\ddot{\theta} + 2\dot{r}\dot{\theta}) &= 0 & \textcircled{2} \end{aligned}$$

NOTE: $\textcircled{2}$ can be written as $\frac{d}{dt}(\underbrace{m r^2 \dot{\theta}}_l) = 0$ $\dot{\theta} = \frac{l}{m r^2}$

* let $u = \frac{1}{r}$: $\frac{du}{d\theta} = -\frac{1}{r^2} \frac{dr}{d\theta} = -\frac{1}{r^2} \frac{dr}{dt} \frac{dt}{d\theta} = -\frac{1}{r^2} \frac{\dot{r}}{\dot{\theta}} = -\frac{M}{l} \dot{r}$ \textcircled{a}

$$\frac{d^2 u}{d\theta^2} = -\frac{M}{l} \frac{d}{d\theta}(\dot{r}) = -\frac{M}{l} \frac{dt}{d\theta} \frac{d}{dt}(\dot{r}) = -\frac{M}{l} \frac{1}{\dot{\theta}} \ddot{r} = -\frac{M^2}{l^2} r^2 \ddot{r} \quad \textcircled{b}$$

$$\textcircled{b} \Rightarrow \ddot{r} = -\frac{l^2}{M^2} u^2 \frac{d^2 u}{d\theta^2}$$

$$* r\dot{\theta}^2 = r \frac{l^2}{M^2 r^4} = \frac{l^2}{M^2 r^3} = \frac{l^2}{M^2} u^3$$

plug into eqn $\textcircled{1}$
& simplify a bit.

$$\Rightarrow \frac{d^2 u}{d\theta^2} + u = -\frac{\mu}{l^2} \frac{1}{u^2} F\left(\frac{1}{u}\right)$$

$$\text{or } u = \frac{1}{r}$$

$$\boxed{\frac{d^2}{d\theta^2} \left(\frac{1}{r}\right) + \frac{1}{r} = -\frac{\mu r^2}{l^2} F(r)} \quad **$$

Ex: $F(r) = -\frac{k}{r^2} = -k u^2 \quad u'' + u = C \quad C = \frac{k\mu}{l^2}$

$$u(\theta) = u_{HG} + u_{IHG}$$

$$u''_{HG} + u_{HG} = 0 \Rightarrow u_{HG} = A \cos(\theta - \delta) \quad A, \delta \text{ from IC's}$$

$$u_{IHG} = C$$

$$\Rightarrow u(\theta) = A \cos(\theta - \delta) + C$$

$$\text{or } \boxed{\frac{1}{r} = A \cos(\theta - \delta) + C}$$

* Centrifugal energy + the Effective Potential

$$E = \frac{1}{2} m \dot{r}^2 + \underbrace{\frac{l^2}{2\mu r^2}}_{V_{\text{eff}}(r)} + U(r)$$

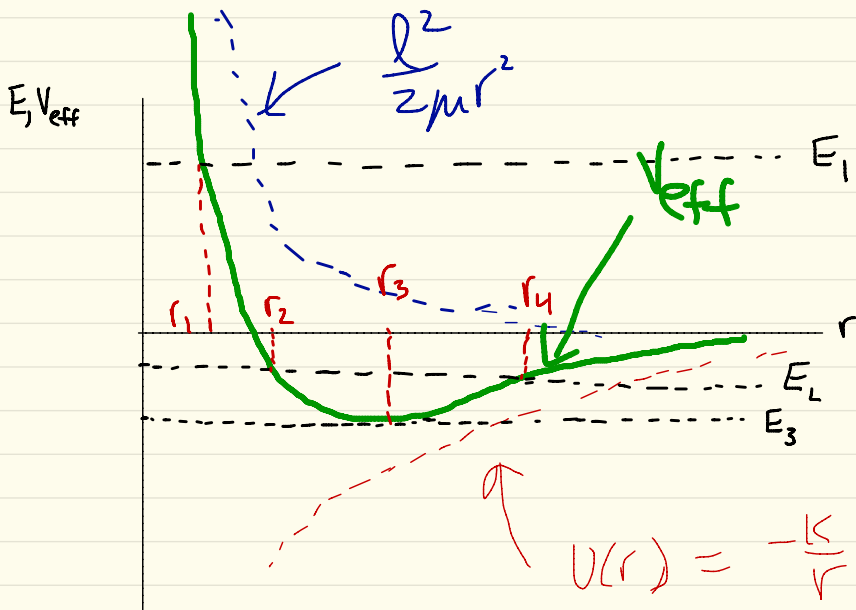
Quasi 1-D problem like
in ch. 2,3

$$= m r \dot{\theta}^2 = \frac{\mu v_{\theta}^2}{r}$$

"Centrifugal force"

$$\text{i.e., } F_{\text{eff}}(r) = -\frac{dV_{\text{eff}}}{dr} = \underbrace{\frac{l^2}{\mu r^3}}_{\text{centrifugal force}} + F(r)$$

*Just like we did in ch 2,3, when we studied 1d motion with $E = \frac{1}{2}mv^2 + U(x)$, we can make qualitative statements about the possible motions by involving energy arguments



① $E_1 > 0$: Unbound motion

② $V_{\text{eff}}^{\text{min}} < E_2 < 0$ $r_2 \leq r \leq r_4$ bounded "apsidal distances"

③ $E_3 = V_{\text{eff}}^{\text{min}}$ $r = r_3$ (circular motion)

$$F_{\text{eff}} = - \left. \frac{\partial V_{\text{eff}}}{\partial r} \right|_{r_3} = 0 = \frac{mV_0^2}{r} - \frac{K}{r^2}$$

* Note for the present $U(r) = -\frac{k}{r}$ example,

$$V_{\text{eff}}^{\text{min}} = -\frac{\mu k^2}{2l^2}$$

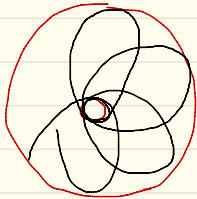
\Rightarrow impossible to have $E < V_{\text{eff}}^{\text{min}}$

as

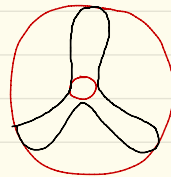
$$E - V_{\text{eff}} = \frac{1}{2} \mu \dot{r}^2$$

$\Rightarrow \dot{r}^2 < 0$ impossible.

* Back to bounded motion (E_2 case) between r_2, r_4



open orbit, never repeats



closed orbit repeats after finite # oscillation