

PHY422/820: Classical Mechanics

FS 2021

Homework #11 (Due: Nov 19)

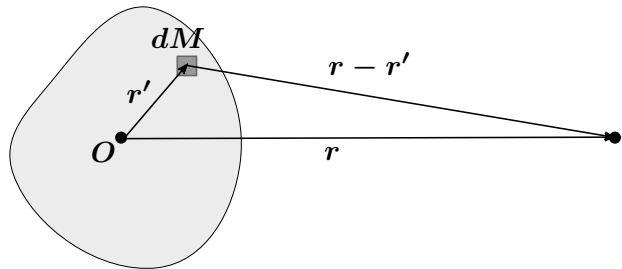
November 21, 2021

Problem H21 – Gravitational Potential of Extended Objects

[15 points] The gravitational potential between a mass m at the point \mathbf{r} and a general mass distribution $\rho(\mathbf{r})$ can be obtained from

$$V(\mathbf{r}) = -Gm \int d^3r' \frac{\rho(\mathbf{r}')}{|\mathbf{r} - \mathbf{r}'|} \quad (1)$$

(see figure, where $dM = \rho dV$ at a given point \mathbf{r}').



1. Show that for $|\mathbf{r}| \gg |\mathbf{r}'|$, we can perform a **multipole expansion** of the potential,

$$V(\mathbf{r}) = -Gm \left(\frac{M}{r} + \frac{\mathbf{d} \cdot \mathbf{r}}{r^3} + \frac{1}{2} \frac{\mathbf{r} \cdot \mathbf{Q} \cdot \mathbf{r}}{r^5} + \dots \right) \quad (2)$$

where the **mass dipole moment** is defined as

$$\mathbf{d} = \int d^3r \rho(\mathbf{r}) \mathbf{r}. \quad (3)$$

and the (Cartesian) **mass quadrupole tensor** \mathbf{Q} is defined componentwise as

$$Q_{ij} = \int d^3r \rho(\mathbf{r}) (3r_i r_j - r^2 \delta_{ij}). \quad (4)$$

HINT: Perform a Taylor expansion of the integrand around $\mathbf{r}' = 0$. Evaluate the required partial derivatives in Cartesian coordinates.

2. How is \mathbf{d} related to the center of mass of the mass distribution? What happens if we switch to the center-of-mass frame?
3. Show that the quadrupole tensor is related to the moment-of-inertia tensor by

$$Q_{ij} = -(3I_{ij} - (\text{tr } \mathbf{I}) \delta_{ij}). \quad (5)$$

What happens if all principal moments of inertia are identical?

Problem H22 – Coupled Oscillators on a Circle

[15 Points] Consider three identical masses m that can move on a circular track of radius R (see figure). Each of the masses is coupled to its neighbors by identical springs with constant k . In static equilibrium, the three masses will form an equilateral triangle, and the length of the springs will be $\frac{2\pi R}{3}$.

1. Show that the Lagrangian can be expressed (up to an irrelevant constant) directly in terms of the *displacements from equilibrium* ϕ_i as

$$L = \frac{1}{2}mR^2 (\dot{\phi}_1^2 + \dot{\phi}_2^2 + \dot{\phi}_3^2) - \frac{1}{2}kR^2 [(\phi_2 - \phi_1)^2 + (\phi_3 - \phi_2)^2 + (\phi_1 - \phi_3)^2]. \quad (6)$$

HINT: Make the ansatz $q_i(t) = R(\phi_{i0} + \phi_i(t))$, where the ϕ_{i0} indicate the absolute angles in static equilibrium.

2. Derive the equations of motion for the angles ϕ_i .
3. Determine the normal modes, i.e., characteristic frequencies and vectors (vectors do not need to be normalized). Interpret your solutions.

