

Harmonic oscillator expanded

$$L = \frac{1}{2} m \dot{x}^2 - \frac{1}{2} m \omega^2 x^2$$

$$p = \frac{\partial L}{\partial \dot{x}} = m \dot{x} \rightarrow \dot{x} = \frac{p}{m}$$

$$\Rightarrow H = \frac{p^2}{2m} + \frac{1}{2} m \omega^2 x^2 = \frac{p^2}{2m} + \frac{1}{2} m \omega^2 x^2$$

$$\Rightarrow \frac{\partial H}{\partial p} = \frac{p}{m} = \dot{x} \Rightarrow p = m \dot{x} \text{ (cf. above)}$$

$$\frac{\partial H}{\partial x} = m \omega^2 x = -\ddot{p} \Rightarrow m \ddot{x} = -m \omega^2 x \Rightarrow \ddot{x} + \omega^2 x = 0$$

$$x(t) = x_0 \cos(\omega t + \phi_x)$$

$$\Rightarrow p^{(t)} = -m \omega x_0 \sin(\omega t + \phi_x)$$

$$\approx p_0 \cos(\omega t + \phi_p)$$

$$\ddot{p} = -m \omega^2 \dot{x} = -\omega^2 p \Rightarrow \ddot{p} + \omega^2 p = 0 \Rightarrow p(t) = p_0 \cos(\omega t + \phi_p)$$

$$\rightarrow x(t) = -\frac{p_0}{m \omega} \sin(\omega t + \phi_p)$$

We also know $\frac{\partial H}{\partial t} = 0 \Rightarrow H = \text{const} = E$

↑
here ... not in general!

$$\Rightarrow 1 = \frac{H}{E} = \frac{p^2}{2mE} + \frac{q^2}{2E/m\omega^2} \quad \text{ellipse in phase space}$$

Handwritten scribbles and notes at the bottom of the page.

Ex. ⁽¹⁾ Harmonic Oscillator

$$L = \frac{1}{2} m \dot{x}^2 - \frac{1}{2} m \omega^2 x^2$$

$$p = \frac{\partial L}{\partial \dot{x}}$$

new version below.

$$H = \frac{p^2}{m} - \frac{p^2}{2m} + \frac{1}{2} m \omega^2 x^2 = \frac{p^2}{2m} + \frac{1}{2} m \omega^2 x^2$$

interesting side note. introduce

$$x_0 = \sqrt{\frac{1}{m\omega}}, p_0 = \sqrt{m\omega}$$

$$\frac{H}{\omega} = \frac{p^2}{2m\omega} + \frac{1}{2} m \omega x^2$$

$$x_0 = \sqrt{\frac{1}{m\omega}}, p_0 = \sqrt{m\omega}$$

$$= \frac{1}{2} \frac{p^2}{p_0^2} + \frac{1}{2} \frac{x^2}{x_0^2}$$

The Virial Theorem

Mean value of a function $f(t)$:

$$\langle f \rangle = \lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T f(t) dt$$

specifically for periodic functions:

$$\langle f \rangle = \frac{1}{T} \int_0^T f(t) dt$$

$$\left(\Leftrightarrow \langle \sin^2 x \rangle = \frac{1}{2\pi} \int_0^{2\pi} \sin^2 x dx = \frac{1}{2} \right)$$

Now consider a mechanical system with $(q_j, p_j), j=1, \dots, n$; with Hamiltonian $H(q_j, p_j, t)$. Define the virial

~~$$V = \sum_i q_i \frac{\partial H}{\partial q_i}$$~~

$$V = \sum_j q_j p_j = - \sum_j q_j \frac{\partial H}{\partial q_j}$$

~~$$V = \sum_j p_j \frac{\partial H}{\partial p_j}$$~~

In certain cases, V can be related to dynamical quantities:

Virial Theorem

If $q_j(t), p_j(t)$ are bounded and if

$$\left\langle \sum_i q_i \frac{\partial H}{\partial q_i} \right\rangle, \left\langle \sum_j p_j \frac{\partial H}{\partial p_j} \right\rangle \text{ exist separately, they}$$

must be equal.

$$\left\langle \sum_j q_j \frac{\partial H}{\partial q_j} \right\rangle = \left\langle \sum_j p_j \frac{\partial H}{\partial p_j} \right\rangle$$

Proof

$$G(t) \equiv \sum_j p_j q_j(t) \quad \text{bounded since } q, p \text{ bounded}$$

$$\Rightarrow \frac{dG}{dt} = \sum_i p_i \dot{q}_i + \sum_i \dot{p}_i q_i = \sum_j p_j \frac{\partial H}{\partial p_j} - \sum_i q_i \frac{\partial H}{\partial q_i}$$

$$\Rightarrow \left\langle \frac{dG}{dt} \right\rangle = \left\langle \sum_j p_j \frac{\partial H}{\partial p_j} - \sum_i q_i \frac{\partial H}{\partial q_i} \right\rangle$$

$$\left\langle \frac{dG}{dt} \right\rangle = \lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T \frac{dG}{dt} dt = \lim_{T \rightarrow \infty} \frac{G(T) - G(0)}{T} = 0$$

$$\Rightarrow \left\langle \sum_j p_j \frac{\partial H}{\partial p_j} - \sum_i q_i \frac{\partial H}{\partial q_i} \right\rangle = 0$$

If mean values exist separately

$$\left\langle \sum_j p_j \frac{\partial H}{\partial p_j} \right\rangle - \left\langle \sum_i q_i \frac{\partial H}{\partial q_i} \right\rangle = 0$$

Applications:

Central Force, bounded orbit:

$$H = T + V = \frac{\vec{p}^2}{2m} + V(r)$$

$$\Rightarrow \left\langle \vec{p} \cdot \frac{\vec{p}}{m} \right\rangle = \left\langle \vec{r} \cdot \nabla V(r) \right\rangle = \left\langle \vec{r} \cdot \left(\frac{dV}{dr} \frac{\vec{r}}{r} \right) \right\rangle = \left\langle r \frac{dV}{dr} \right\rangle$$

For $V(r) = \frac{A}{r^n}$, this equation becomes

$$2\langle T \rangle = -n \left\langle r \frac{A}{r^{n+1}} \right\rangle = -n \langle V \rangle$$

$$\Rightarrow \langle T \rangle = -\frac{n}{2} \langle V \rangle$$

For $n=1$, i.e., Kepler or Coulomb

$$\langle T \rangle = -\frac{1}{2} \langle V \rangle, \quad \langle E \rangle = \langle T \rangle + \langle V \rangle$$

Oscillator: $n=2$

$$= -\frac{1}{2} \langle V \rangle + \langle V \rangle = \frac{\langle V \rangle}{2}$$

$$\langle T \rangle = \langle V \rangle$$

$$= -\langle T \rangle$$

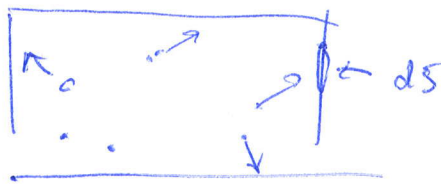
$$\Rightarrow \langle E \rangle = 2\langle T \rangle = 2\langle V \rangle$$

bound states have positive energy.

bound states have negative energy since $T > 0$

Equation of State of an Ideal Gas

Skip



Gas molecules experience forces when they hit the wall:

$$d\vec{F} = -P \hat{n} dS \leftarrow \text{surface}$$

↑ pressure
↑ surface normal

$$\Rightarrow 2 \langle T \rangle = - \left\langle \sum_i \vec{r}_i \cdot \vec{F}_i \right\rangle \rightarrow - \oint_S \vec{r} \cdot d\vec{F} = \oint_S P \vec{r} \cdot \hat{n} dS$$

continuous limit &
~~steady state~~ $P = \text{const.}$
 (takes care of time int.)

But Gauss' law/divergence theorem

$$\oint_S \vec{r} \cdot \hat{n} dS = \int_V \nabla \cdot \vec{r} dV = \int_V \left(\frac{\partial x}{\partial x} + \frac{\partial y}{\partial y} + \frac{\partial z}{\partial z} \right) dV = 3V$$

$$\Rightarrow 2 \langle T \rangle = 3PV$$

Equipartition principle: energy per molecule with three d.o.f. is $\frac{3}{2} k_B T$ with Boltzmann const. k_B and temperature T , so

~~$$2 \cdot \frac{3}{2} k_B T \cdot N = 3PV$$~~

$$\Rightarrow N k_B T = PV$$

Hamilton's Eqs. from the Variational principle

$$\delta S = \delta \int_{t_1}^{t_2} L(q_i, \dot{q}_i, t) dt = 0$$

$$\rightarrow \delta S = \delta \int_{t_1}^{t_2} \left(\sum_k p_k \dot{q}_k - H(q_j, p_j, t) \right) dt = 0$$

path variations are now in phase space, $\delta q_i, \delta p_i$ are independent

$$\Rightarrow \delta S = \int_{t_1}^{t_2} \sum_k \left(p_k \delta \dot{q}_k + \dot{q}_k \delta p_k - \frac{\partial H}{\partial q_k} \delta q_k - \frac{\partial H}{\partial p_k} \delta p_k \right) dt = 0$$

(Recall: no time variation for δ)

integrate by parts:

$$\int_{t_1}^{t_2} p_k \delta \dot{q}_k dt = \underbrace{p_k \delta q_k}_{=0} \Big|_{t_1}^{t_2} - \int_{t_1}^{t_2} \dot{p}_k \delta q_k dt$$

($\delta q(t_2) = \delta q(t_1) = 0$) But note that we do not need $\delta p(t_1) = \delta p(t_2) = 0$ here!!

$$\Rightarrow \delta S = \int_{t_1}^{t_2} \sum_k \left(\left(\dot{p}_k + \frac{\partial H}{\partial q_k} \right) \delta q_k + \left(\dot{q}_k - \frac{\partial H}{\partial p_k} \right) \delta p_k \right) dt = 0$$

\rightarrow independent variations \Rightarrow

$$\dot{p}_k + \frac{\partial H}{\partial q_k} = 0, \quad \dot{q}_k - \frac{\partial H}{\partial p_k} = 0$$

$$\hookrightarrow f(q_i, p_i, \dot{q}_i, \dot{p}_i, t) \equiv \sum_{k=1}^n p_k \dot{q}_k - H(q_j, p_j, t)$$

$$\Rightarrow \frac{d}{dt} \frac{\partial f}{\partial \dot{q}_i} - \frac{\partial f}{\partial q_i} = 0 \Rightarrow \dot{p}_i + \frac{\partial H}{\partial q_i} = 0 \quad \begin{array}{l} \text{only first term depends on } \dot{q}_i \\ \text{only second term on } q \end{array}$$

$$\frac{d}{dt} \underbrace{\frac{\partial f}{\partial \dot{p}_i}}_{=0} - \frac{\partial f}{\partial p_i} = 0 \Rightarrow \dot{q}_i + \frac{\partial H}{\partial p_i} = 0$$

From variational principle, it is clear that $f' = f + \frac{df}{dt}$ will yield the same Hamilton eqs.