# The Python interpreter

Daniel Winklehner, Remi Lehe

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S. M. Lund, J.-L. Vay, D. Bruhwiler, R. Lehe & D. Winklehner
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## Python interpreter: Outline

1. Overview of the Python language
2. Python, numpy and matplotlib
3. Reusing code: functions, modules, classes
4. Faster computation: Forthon



## Overview of the Python programming language

- **Interpreted language** (i.e. not compiled)
  → Interactive, but not optimal for computational speed
- **Readable and non-verbose**
  No need to declare variables
  Indentation is enforced
- **Free and open-source**
  + Large community of open-souce packages
- **Well adapted for scientific and data analysis applications**
  Many excellent packages, esp. numerical computation (`numpy`), scientific applications (`scipy`), plotting (`matplotlib`), data analysis (`pandas, scikit-learn`)

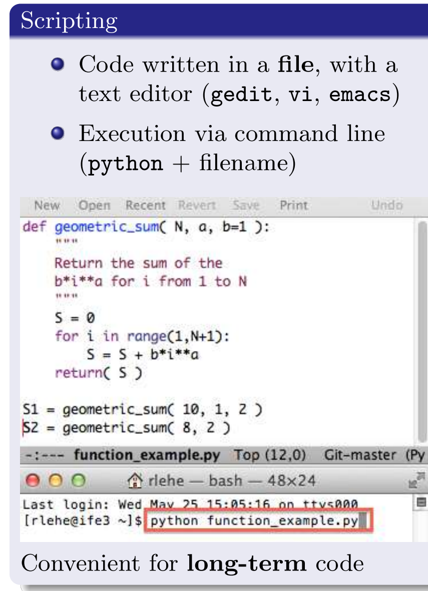




## Interfaces to the Python language

### Scripting

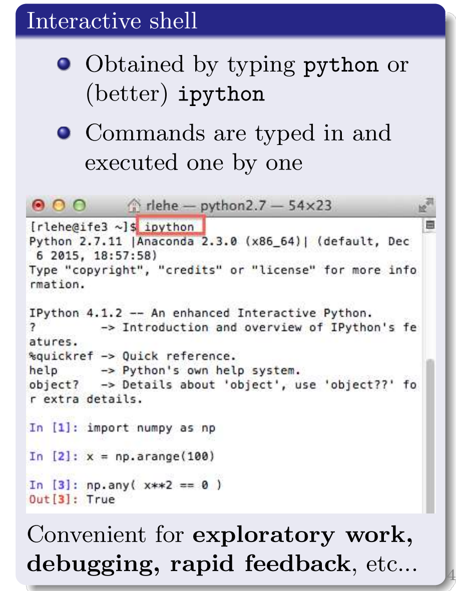
- Code written in a **file**, with a text editor (`gedit`, `vi`, `emacs`)
- Execution via command line (`python` + filename)




Convenient for **long-term** code

### Interactive shell

- Obtained by typing `python` or (better) `ipython`
- Commands are typed in and executed one by one




Convenient for **exploratory work, debugging, rapid feedback**, etc...

## Interfaces to the Python language

### IPython (a.k.a Jupyter) notebook

- Notebook interface, similar to `Mathematica`.
- Intermediate between **scripting** and **interactive shell**, through **reusable cells**
- Obtained by typing `jupyter notebook`, opens in your web browser

Convenient for **exploratory work, scientific analysis and reports**





## PyCharm Integrated Development Environment (IDE)

https://www.jetbrains.com/pycharm/





## Python 2 vs. Python 3

### A Quick Note

A lot of python based software still supports both versions of python, but better start new projects in python 3.x for future compatibility.

### python 2.7.x

- `print "Hello World"`
- **Division:** Integer division yields **int** results ("floor division")
- **implicit relative import** `from module import function`

### python 3.x

- `print("Hello World")`
- **Division:** All divisions yield **float** results ("true division")
- **explicit relative import** `from .module import function`





## Overview of the Python language

### This lecture

**Reminder** of the main points of the **Scipy lecture notes** through an example problem.

### Example problem: Euler's method

Use Euler's method to **numerically integrate**, between $t = 0$ and 10:

$$\frac{d\,x(t)}{dt} = x(t)\cos(t) \qquad \text{with} \qquad x(0) = 1$$

Compare it with the exact solution: $x(t) = e^{\sin(t)}$

**Reminder:** In this case, Euler's method gives:

$$t_i = i\Delta t$$
$$x_i = x_{i-1} + \Delta t \times x_{i-1}\cos(t_{i-1})$$

$x_0 = 1$ $x_1$ $x_2$ $x_3$ $\dots$ $\Delta t$ $t$

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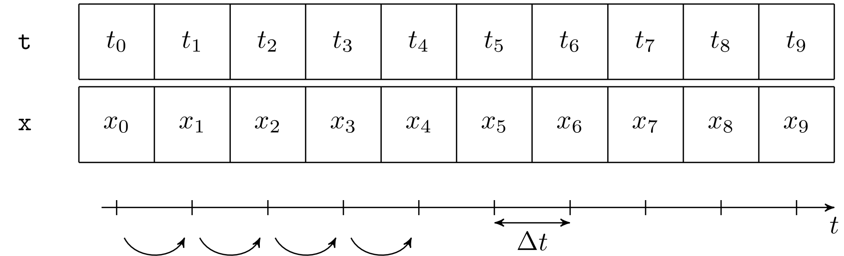
# Example problem: Structure of the code

**Storage in memory:**




**For loop:**

Repeatedly apply: $x_i = x_{i-1} + \Delta t \times x_{i-1} \cos(t_{i-1})$





# Numpy arrays

**Numpy arrays**

Provide efficient **memory storage** and **computation**, for large number of elements of the same type.

- Standard import: `import numpy as np`
- Creation of numpy arrays:
  `np.arange`, `np.zeros`, `np.random.rand`, `np.empty`, etc...
  (In `ipython`, use e.g. `np.arange?` to read the documentation)
- Individual elements are accessed with square brackets:
  `x[i]` (1D array), `y[i,j,k]` (3D array)
  **For an array with `N` elements, the indices start at `0` (included) and end at `N-1` (included)**
- Subsets of the array are accessed using **slicing syntax**:
  `x[` *start index* `:` *end index* `:` *step* `]` ; in particular:
  - `x[` *start index* `:` *end index* `]` : slicing with step 1 by default
  - `x[ :` *end index* `]` : slicing with start index 0 by default
  - `x[` *start index*`:` -1 `]` : slicing up to the last-but-one element





# For loops

**For loop**

Repeatedly perform a given operation
(e.g. apply the same operation to every element of a numpy array)

**Syntax:**

`for i in range(` *start index* `,` *end index* `,` *step* `):`
    *Perform some operation that depends on* `i`

- Indentation and the use of column (`:`) are key.
- The `range` function can be used with 1, 2 or 3 arguments:
  - `range(N)`: loop from index `0` to index `N-1` (included)
  - `range(i,N)`: loop from index `i` to index `N-1` (included)
  - `range(i,N,k)`: loop from index `i` to index `N-1` with step `k`
- In the above, `range` can also be replaced by a list or any iterable.

# Numpy and for loops: task

**Task 1**

In a text editor, write a python script (named `euler.py`) which:

- Sets the number of integration steps to `N = 200`, and the timestep to `dt = 10./N`
- Initializes the array `t` (with `N` elements) using `np.arange` so that

$$t_i = i\Delta t$$

- Initializes the array `x` (with `N` elements) using `np.empty` and setting the initial point `x[0]` to 1.
- Loops through the array `x` and applies Euler's method: (Here, the loop should start at $i = 1$, not $i = 0$)

$$x_i = x_{i-1} + \Delta t \times x_{i-1} \cos(t_{i-1})$$

Run the script (`python euler.py`), to check that there is no error.





# Comparison with the exact solution

| t | $t_0$ | $t_1$ | $t_2$ | $t_3$ | $t_4$ | $t_5$ | $t_6$ | $t_7$ | $t_8$ | $t_9$ |
|---|---|---|---|---|---|---|---|---|---|---|
| x | $x_0$ | $x_1$ | $x_2$ | $x_3$ | $x_4$ | $x_5$ | $x_6$ | $x_7$ | $x_8$ | $x_9$ |
| x_exact | $e^{\sin(t_0)}$ | $e^{\sin(t_1)}$ | $e^{\sin(t_2)}$ | $e^{\sin(t_3)}$ | $e^{\sin(t_4)}$ | $e^{\sin(t_5)}$ | $e^{\sin(t_6)}$ | $e^{\sin(t_7)}$ | $e^{\sin(t_8)}$ | $e^{\sin(t_9)}$ |

We wish to compare the two results by:

- Calculating the RMS error:

$$\epsilon_{RMS} = \sqrt{\frac{1}{N}\sum_{i=0}^{N-1}(x_i - x_{exact,i})^2}$$

- Plotting $x$ and $x_{exact}$ versus $t$.





# Numpy arrays: element-wise operations

**Element-wise operation**

Operation that is repeated for each element of an array **and does not depend on previous/next elements**.

e.g. $$x_{exact,i} = e^{\sin(t_i)} \qquad \forall i \in [0, N-1]$$

- Could be done with a `for` loop:

```
for i in range(N):
    x_exact[i] = np.exp( np.sin( t[i] ) )
```

- But is **computationally faster** with numpy vector syntax:

```
x_exact = np.exp( np.sin( t ) )
```

Numpy vector syntax also works for the element-wise operations: `+`, `-`, `*`, `/`, `**` (power), `np.sqrt` (square-root), `np.log`, etc...





# Numpy arrays: reduction operations

**Reduction operation**

Operation that extracts a single scalar from a full array

e.g. $$S = \sum_{i=0}^{N-1} y_i$$

- Again, could be done with a `for` loop:

```
S = 0
for i in range(N):
    S = S + y[i]
```

- But is **computationally faster** with numpy reduction methods

```
S = np.sum( y )
```

Other reduction operations:
`np.product`, `np.max`, `np.mean`, etc... (for real or integer arrays)
`np.any`, `np.all`, etc... (for boolean arrays)

## Plotting package: matplotlib

Other Python plotting packages: `pygist`, `bokeh`, `seaborn`, `bqplot`, ...

**Pros of matplotlib**

- Publication-quality figures
- Extremely versatile and customizable
- **Standard plotting package in the Python community**

**Cons of matplotlib**

- Slow
- Sometimes verbose
- Limited interactivity

- Standard import: `import matplotlib.pyplot as plt`
- Basic plotting commands:
  `plt.plot( t, x )` (plots 1darray `x` as a function of 1darray `t`)
- Show the image to the screen:
  `plt.show()` (unneeded when using `ipython --matplotlib`)
- Save the figure to a file:
  `plt.savefig(` *file name* `)`





## Numpy and matplotlib: task

**Task 2**

In a text editor, add the following features to `euler.py`:

- Create the array `x_exact` so that $x_{exact,i} = e^{\sin(t_i)}$
- Calculate the RMS error, without using any for loop:

$$\epsilon_{RMS} = \sqrt{\frac{1}{N}\sum_{i=0}^{N-1}(x_i - x_{exact,i})^2}$$

  Use the `print` statement, to show the value of the RMS error
- Plot $x$ and $x_{exact}$ as a function of $t$ on the same figure, and show it to the screen. (Use `plot(t, x_exact, '--')` to show the exact solution with dashed lines.)

Run the script (`python euler.py`), to check that it works.



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## Reusing code for the example problem

**Example problem**

Compare the results of Euler's method for different values of `N` (and thus of `dt`) **on the same plot**.

→ Not possible with the code from task 2
(unless we copy and paste a lot of code)

We need to make the code more **abstract** and **reusable**:

- Define **functions** that depend on `N` and initialize the arrays, perform Euler integration, and plot the results.
- Place these functions inside a **module** so that they can be imported and used elsewhere.

# Functions

**Example for function definition**

```
def geometric_sum( N, a, b=1 ):
    """
    Return the sum of the
    b*i**a for i from 1 to N
    """
    S = 0
    for i in range(1,N+1):
        S = S + b*i**a
    return( S )
```

**Example for function call**

```
S1 = geometric_sum( 10, 1, 2 )
S2 = geometric_sum( 8, 2 )
```

- **Key syntax:** `def`, `()` and `:`, the body is indented
- The **"docstring"** is optional. Users can see it in `ipython` with `geometric_sum?` or `help(geometric_sum)`
- Here, `b` has a **default value**, which is used when only 2 arguments are given
- Functions can also return **several objects** (e.g. `return(x, a, b)`) or **nothing** (no `return` statement)
- Similarly, functions can be defined with **no arguments**





# Functions: task

**Task 3**

Reorganize the script `euler.py` so as to make the code reusable:

- Start with the import statements (`numpy` and `matplotlib`)
- Write a function with signature `initialize_arrays(N, T=10.)` which sets `dt = T/N`, initializes `t` and `x`, and returns `t`, `x`, `dt`
- Write a function `euler_integration( t, x, dt, N )`, which fills the array `x` (this function does not return anything)
- Write a function `evaluate_result(t, x, N)`, which computes the exact result, prints the RMS error, and plots the arrays
- Then set `N1 = 100`, `N2 = 200` and create the corresponding variables `t1,x1,dt1` and `t2,x2,dt2` with `initialize_array`.
- Then call `euler_integration` and `evaluate_result` on each set of arrays and values. Compare the results.

Type `python euler.py` to check that the final section runs.





# Classes: Introduction

**From the previous task...**

```
N1 = 100
N2 = 200
t1, x1, dt1 = initialize_arrays( N1 )
t2, x2, dt1 = initialize_arrays( N1 )

euler_integration( t1, x1, dt1, N1 )
euler_integration( t2, x2, dt2, N2 )

evaluate_result( t1, x1, N1 )
evaluate_result( t2, x2, N2 )
```

Although the code works, note that it is tedious to:

- create 4 different variables with a suffix 1 or 2
- pass these variables as arguments to the different functions

This is solved by **object-oriented programming** and **classes**.





# Classes: initialization and attributes

**Example of class definition**

```
class EulerSolver(object):

    def __init__(self, N):
        "Initialize attributes"
        x = np.empty(N)
        x[0] = 1
        self.N = N
        self.x = x
```

**Example of use**

```
solver1 = EulerSolver(100)
solver2 = EulerSolver(200)
print solver1.N
print solver2.N
print solver1.x
```

- Classes are **"containers"**: Variables are **encapsulated** together as **attributes** of an **instance** of the class.
- **Creation of an instance** (e.g. `EulerSolver(100)`) executes the code in `__init__`.
- **Accessing attributes** replace `self` by the name of the instance.
- **Predefined syntax:** Use the keywords `class`, `(object):` and `__init__` Note that `__init__` takes `self` as first argument when defined, but this is skipped when creating an instance.

## Classes: methods

**Example of class definition**

```
class EulerSolver(object):

    def __init__(self, N):
        x = np.empty(N)
        x[0] = 1
        self.N = N
        self.x = x

    def euler_integration(self, dt):
        for i in range(1,self.N):
            self.x[i] = self.x[i-1] + \
              dt * self.x[i-1] * \
              np.cos( (i-1)*dt )
```

**Example of use**

```
solver1 = EulerSolver(100)
solver1.euler_integration( 0.1 )
```

- **Methods** are functions which can access the **attributes** of a class.
  → The attributes do not need to be passed as arguments.
- **Syntax for definition**
  Pass `self` as first arguments, then use `self.` to access attributes
- **Syntax for calling**
  Prefix with name of the instance, then skip `self` in arguments





## Classes: task

**Task 4**

Rewrite `euler.py` so as to define a class `EulerSolver`

- Replace the function `initialize_arrays` by a corresponding method `__init__(self, N, T=10.)` This method should define `N, x, t, dt` as attributes.
- Replace the functions `euler_integration` and `evaluate_result` by methods with the same name respectively. These methods should take no argument (besides `self`), but should use the attributes through the `self.` syntax.
- Compare again `N=100` and `N=200`, by creating corresponding instances of `EulerSolver` and calling their methods.





## References

**Scipy lecture notes:**
`http://www.scipy-lectures.org/` (G. Varoquaux et al., 2015)

**Python tutorial:**
`https://docs.python.org/3/tutorial/` (Python Software foundation, 2016)

**Forthon:**
`https://github.com/dpgrote/Forthon` (D. Grote et al., 2016)